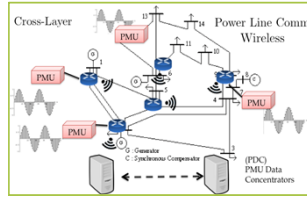
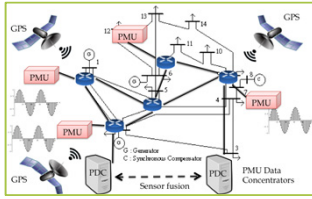


GOALS

- Provide scalable primitives for accurate network timing for Networked Industrial Control Systems (NICS).
- Provide coordination mechanisms for scheduling (important for protection schemes in the grid).
- Attain those goals with a decentralized design.
- Create a design inspired by the biological pulse coupled oscillators (PCO) model, feature properties of natural swarms, such as:
 - Scalable designs.
 - Physical signaling and timing estimation accuracy.
 - Self-healing, adaptive.
 - Decentralized (ad hoc networks).



FUNDAMENTAL QUESTIONS/CHALLENGES

- PCO primitives can lead to two useful emergent behaviors:
 - **Synchronization**
 - Nodes are attracted to fire a beacon signal in unison as long as they are in a connected graph.
 - Potentially useful to establish common timing.
 - Are the synchronization speed and accuracy sufficient for accurate phasor measurement unit (PMU) synchronization?
 - Is the protocol robust to attacks and failures?
 - **De-synchronization**
 - Nodes are attracted to fire their beacons in a daisy chain.
 - Useful to establish a wake-up or collision-free access schedule (Time Division Multiplexing).
 - Is the scheduling protocol mindful of hidden and exposed terminal problems?
 - Is it sufficiently fast in adapting to a changed environment?
 - Is it efficient in sharing resources?
- Can we have a control plane that provides both Network Time and Access control via PCO and harmonize communications in Networked Industrial Control Systems (NICS)?

RESEARCH PLAN

- Combine PCO primitives into a PCO Network Timing and Access Protocol (PCO-NTAP) to attain two goals:
 - 1) Accurate and secure timing.
 - 2) Reliable, deterministic, conflict-free access.
- PCO NTAP protocol design compatible with master/slave communications (e.g., Remote Terminal Units and Intelligent Electronic Devices) orchestrated by application layers such as DNP3 or Modbus.
 - Routing topologies: multiple coexisting clusters and trees.
- Analyze the convergence and efficiency (rate for shared networks).
- Analyze the timing accuracy.
- Introduce security measures (signal scrambling and intrusion detection).
- Design a prototype of the PCO-NTAP.
 - Wake-up radio, separating control + synchronization from the data plane and making it back-compatible with other radios used in NICS.

RESEARCH RESULTS

PCO synchronization and De-synchronization basics

• State of the clock $\Phi_i(t)$ - the node fires when $\Phi_i(t) = 1$

$$\Phi_i(t) = \left(\frac{t}{T_{PCO}} + \phi_i \right) \bmod 1$$

• If a firing is detected at time t_f the PCO update is

$$\Phi_i^+(t_f) = ((1 + \alpha)\Phi_i(t_f) \bmod 1)$$

Excitatory $\alpha > 0$ Inhibitory $\alpha < 0$

Mesh Networks

• Clock cycle and state of node i

PCO Network Time and Access Protocol – PCO NTAP

- Each node and cluster-head has an internal timer ($u \in \mathcal{V} \cup \mathcal{C}$):

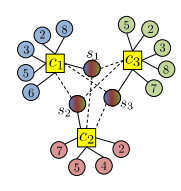
$$\Phi_u(t) = (t - \phi_u) \frac{L}{T} \pmod{L}$$

- Timer evolutions can be decomposed into discrete and continuous parts

Scheduled by PCO Desync Aligned by PCO sync

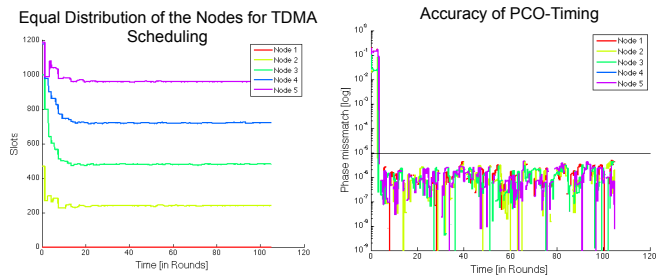
$$\Phi_u(t) = \Phi_u^{(d)}(t) + \Phi_u^{(c)}(t) \pmod{L}$$

clustered networks (master/slave configurations)



Main results: Convergence analysis of PCO NTAP.

- Even if in conflict, nodes settle to locally fair schedules [Ashkiani '12].
- Confirmed by numerical simulations.



$N=5$ nodes are placed randomly in a 2D-plane of $r=1$. Signal-travel-time is assumed to be the speed of light with added normalized Gaussian time error $N(0, 10^{-5})$. Number of slots is set to $L=1200$.

Example: Frame duration $\leq 1/60$ sec., PCO slot $= 1/60/L$ (e.g., 14 μ sec.). Time Error Variance with 6dB of SNR and 20MHz of bandwidth $\sim 6.2797e-16$. While the simulation has noise variance $1.9600e-15$. Distance error negligible below 10 m.

BROADER IMPACT

- A decentralized self-healing radio protocol to support synchronization and scheduling can reduce vulnerabilities due to possible spoofing and jamming of GPS signals and other master/slave network synchronization protocols.
- It can make NICS scalable and easy to deploy because of reliable timing and scheduling of information flow.

FUTURE EFFORTS

- Complete the study of the timing accuracy.
- Consider tree topologies for the communication.
- Study compatibility of PCO-NTAP as a wake-up radio.
- Develop and test the PCO-NTAP hardware implementation.