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## Introduction to<br> \title{ \section*{Introduction to Power System Analysis} 

 Power System Analysis}}

Hui Lin, Siming Guo<br>Hui Lin, Siming Guo


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## tion to

## Agenda

- Power System Notation
- Power Flow Analysis
- Hands on Matpower and PowerWorld


## Simple Power System

- Every power system has three major components
- generation: source of power, ideally with a specified power, voltage, and frequency
- load: consumes power; ideally with constant power consumption
- transmission system: transmits power; ideally as a perfect conductor


## Complications

- No ideal voltage sources exist
- Loads are seldom constant, and we need to balance supply and demand in real time
- Transmission system has resistance, inductance, capacitance and flow limitations
- Simple system has no redundancy so power system will not work if any component fails


## Notation - Power

- Power: Instantaneous consumption of energy
- Power Units
- 

Watts $=$ voltage $\times$ current for $\mathrm{dc}(\mathrm{W})$
kW - $1 \times 10^{3}$ Watt
MW - $1 \times 10^{6}$ Watt
GW - $1 \times 10^{9}$ Watt

- Installed U.S. generation capacity is about 900 GW ( about 3 kW per person)
- Maximum load of Champaign/Urbana about 300 MW


## Notation - Energy

- Energy: Integration of power over time; energy is what people really want (and pay for) from a power system
- Energy Units
- Joule $=1$ Watt-second (J)

- U.S. electric energy consumption is about 3600 billion kWh (about 13,333 kWh per person, which means on average we each use 1.5 kW of power continuously)


## Review of Phasors

Goal of phasor analysis is to simplify the analysis of constant frequency ac systems

$$
\begin{aligned}
& v(t)=\mathrm{V}_{\text {max }} \cos \left(\omega \mathrm{t}+\theta_{\mathrm{v}}\right) \\
& i(t)=\mathrm{I}_{\max } \cos \left(\omega \mathrm{t}+\theta_{\mathrm{I}}\right)
\end{aligned}
$$

Root Mean Square (RMS) voltage of sinusoid

$$
\sqrt{\frac{1}{T} \int_{0}^{T} v(t)^{2} d t}=\frac{V_{\max }}{\sqrt{2}}
$$

## Complex Power

## Power

## Complex Power, cont'd

## Average Power

## Phasor Representation

Euler's identity: $e^{j \theta}=\cos \theta+j \sin \theta$
Phasor notation is developed by
rewriting using Euler's identity

$$
\begin{aligned}
v(t) & =\sqrt{2} V \cos \left(\omega t+\theta_{V}\right) \\
v(t) & =r e\left[\sqrt{2} V e^{j \omega t} e^{\theta_{V}}\right]
\end{aligned}
$$

## Phasor Representation, cont'd

The RMS, cosine-reference phasor is:

$$
\begin{gathered}
\bar{V}=V e^{j \theta}=V \angle \theta_{V} \\
\bar{V}=V\left(\cos \theta_{V}+j \sin \theta_{V}\right) \\
\bar{I}=I\left(\cos \theta_{I}+j \sin \theta_{I}\right)
\end{gathered}
$$

## Complex Power

$$
\begin{gathered}
S=\bar{V} \bar{I}^{*} \\
=V I e^{j\left(\theta_{V}-\theta_{I}\right)} \\
=V I\left[\cos \left(\theta_{V}-\theta_{I}\right)+j \sin \left(\theta_{V}-\theta_{I}\right)\right] \\
=P+j Q
\end{gathered}
$$

$P$ : real power (W, kW, MW)
$Q$ : reactive power (var, kvar, Mvar)
$S$ : complex power (va, kva, Mva)
Power factor $(\mathrm{pf}): \cos \left(\theta_{V}-\theta_{I}\right)$
If current leads voltage, then pf is leading
If current lags voltage then pf is lagging

## Power Flow Analysis



- Bus ----- Transmission Line
(G) Generators $\downarrow$ Loads
- The power flow analysis is the process of solving the steady state of the power system
- Steady state: voltage magnitude and angle for each bus
- Generator: modeled as constant power delivery
- Loads: modeled as constant power consumption
- Transmission line: modeled as constant impedance


## Power Flow Analysis

Busi
( $\bar{V}, \bar{I}$ : the voltage and the current that injects into bus $i$ )

$$
\begin{aligned}
& \bar{I}_{i}=\sum_{k} \bar{I}_{i k} \\
& \bar{I}_{i k}\left.=\frac{\left(\bar{V}_{i}\right.}{}-\bar{V}_{k}\right) \\
& z_{i k}
\end{aligned}
$$

( $k$ takes indices of all buses that connected to bus $i ; Z_{i k}$ specifies the impedance of transmission line connecting bus $i$ and bus $k$ )

## $\boldsymbol{Y}$-Bus (admittance matrix)

$$
\begin{gathered}
I_{i}=\sum_{k} \frac{\left(V_{i}-V_{k}\right)}{z_{i k}}=\sum_{k}\left(V_{i}-V_{k}\right) y_{i k} \\
=\left(-y_{i 1} V_{1}\right)+\left(-y_{i 2} V_{2}\right)+\ldots,\left[\sum_{k}\left(y_{i k}\right) V_{i}\right]+\ldots+\left(-y_{i n}\right) V_{n} \\
=\left[\begin{array}{llllll}
-y_{i 1} & -y_{i 2} & \ldots & \sum_{k} y_{i k} & \ldots & -y_{i n}
\end{array}\right]\left[\begin{array}{c}
V_{1} \\
V_{2} \\
\vdots \\
V_{i} \\
\vdots \\
V_{n}
\end{array}\right]
\end{gathered}
$$

## $\boldsymbol{Y}$-Bus (admittance matrix), cont'd

Write $I_{j}$ for all buses together: $\bar{I}=Y \bar{V}$, where
$\left(\bar{I}=\left[I_{1}, I_{2}, \ldots, I_{n}\right], \bar{V}=\left[V_{1}, V_{2}, \ldots, V_{n}\right]\right)$
Construction of $Y$ :

$$
\begin{gathered}
Y_{i i}=\sum_{k} y_{i k} \\
Y_{i k}=Y_{k i}=-y_{i k} \\
Y=G+j B
\end{gathered}
$$

So we have: $I_{i}=\sum_{k}\left(Y_{i k} V_{k}\right)$

## Power Flow Equation at Bus j

$$
\begin{aligned}
& \text { To other } \\
& \text { buses } \\
& S_{G}-S_{D}=\bar{V}_{i} \bar{I}_{i}{ }^{*}=\bar{V}_{i} \bar{I}_{i}{ }^{*}=\bar{V}_{i} \sum_{k}\left(Y_{i k} \overline{V_{k}}\right)^{*} \\
& =V_{i} e^{j \theta_{i}}\left(\sum_{k}\left(G_{i k}+j B_{i k}\right) V_{k} e^{j \theta_{k}}\right)^{*} \\
& =V_{i} e^{j \theta_{i}} \sum_{k} V_{k}\left(G_{i k}-j B_{i k}\right) e^{-j \theta_{k}} \\
& =\sum_{k} V_{i} V_{k}\left(G_{i k}-j B_{i k}\right) e^{j\left(\theta_{i}-\theta_{k}\right)} \\
& =\sum_{k} V_{i} V_{k}\left(G_{i k} \cos \left(\theta_{i}-\theta_{k}\right)+B_{i k} \sin \left(\theta_{i}-\theta_{k}\right)\right) \\
& +j \sum_{k} V_{i} V_{k}\left(G_{i k} \sin \left(\theta_{i}-\theta_{k}\right)-B_{i k} \cos \left(\theta_{i}-\theta_{k}\right)\right)
\end{aligned}
$$

## Power Flow Equation at Bus j

$$
\begin{aligned}
& P_{G}-P_{D}= \\
& \quad \sum_{k} V_{i} V_{k}\left(G_{i k} \cos \left(\theta_{i}-\theta_{k}\right)+B_{i k} \sin \left(\theta_{i}-\theta_{k}\right)\right) \\
& \mathrm{Q}_{G}-Q_{D}= \\
& \quad \sum_{k} V_{i} V_{k}\left(G_{i k} \sin \left(\theta_{i}-\theta_{k}\right)-B_{i k} \cos \left(\theta_{i}-\theta_{k}\right)\right)
\end{aligned}
$$

- Slack bus:
- $V$ and $\theta$ are known, used as a reference
- PV bus, with generators connected
- $P$ and $V$ are known
- PQ bus, with only load units connected
- $P$ and $Q$ are known


## Solving Power Flow Equations

- Assuming $m-1$ PV buses
- Given: $V_{1}, \theta_{1}, P_{G, 2}, V_{2}, \ldots, P_{G, m}, V_{m}, P_{D, m+1}, Q_{D, m+1}, \ldots$, $P_{D, n}, Q_{D, n}$
- Unknown: $P_{G, 1}, Q_{G, 1}, Q_{G, 2}, \theta_{2}, \ldots, Q_{G, m}, \theta_{m}, V_{m+1}$, $\theta_{m+1}, \ldots, V_{n}, \theta_{n}$


## Newton-Raphson Methods

Assume (m-1) PV buses among $n$ buses

$$
x=\left[\begin{array}{c}
\theta_{2} \\
\theta_{3} \\
\vdots \\
\theta_{n} \\
V_{m+1} \\
V_{m+2} \\
\vdots \\
V_{n}
\end{array}\right] \quad f(x)=\left[\begin{array}{c}
P_{2}(x)-P_{G, 2}+P_{D, 2} \\
P_{3}(x)-P_{G, 3}+P_{D, 3} \\
\vdots \\
P_{n}(x)-P_{G, n}+P_{D, n} \\
Q_{m+1}(x)-Q_{G, m+1}+Q_{D, m+1} \\
Q_{m+2}(x)-Q_{G, m+2}+Q_{D, m+2} \\
\vdots \\
Q_{n}(x)-Q_{G, n}+Q_{D, n}
\end{array}\right]
$$

## Multi-Variable Example

## Multi-variable Example, cont'd

## N-R Power Flow Solution

The most difficult part of the algorithm is determining and inverting the n by n Jacobian matrix, $\mathbf{J}(\mathbf{x})$

$$
\mathbf{J}(\mathbf{x})=\left[\begin{array}{cccc}
\frac{\partial f_{1}(\mathbf{x})}{\partial x_{1}} & \frac{\partial f_{1}(\mathbf{x})}{\partial x_{2}} & \cdots & \frac{\partial f_{1}(\mathbf{x})}{\partial x_{n}} \\
\frac{\partial f_{2}(\mathbf{x})}{\partial x_{1}} & \frac{\partial f_{2}(\mathbf{x})}{\partial x_{2}} & \cdots & \frac{\partial f_{2}(\mathbf{x})}{\partial x_{n}} \\
\vdots & \ddots & \ddots & \vdots \\
\frac{\partial f_{n}(\mathbf{x})}{\partial x_{1}} & \frac{\partial f_{n}(\mathbf{x})}{\partial x_{2}} & \cdots & \frac{\partial f_{n}(\mathbf{x})}{\partial x_{n}}
\end{array}\right]
$$

## Other Power Flow Solution

Divide the Jacobian matrix into four sub-matrices:

$$
J(x)=\left[\begin{array}{ll}
\frac{\partial P}{\partial \theta} & \frac{\partial P}{\partial V} \\
\frac{\partial Q}{\partial \theta} & \frac{\partial Q}{\partial V}
\end{array}\right]
$$

Decoupled power flow:

$$
M(x)=\left[\begin{array}{cc}
\frac{\partial P}{\partial \theta} & 0 \\
0 & \frac{\partial Q}{\partial V}
\end{array}\right]
$$

## Other Power Flow Solution

Fast decoupled power flow, assuming $\theta_{i}-\theta_{k} \approx 0$, $V_{i} \approx 1, G_{i k} \ll B_{i k}$
So we have: $\frac{\partial P}{\partial \theta} \approx-\tilde{B}=-\left[\begin{array}{ccc}B_{22} & \ldots & B_{2 n} \\ \vdots & \vdots & \vdots \\ B_{n n} & \ldots & B_{n n}\end{array}\right]$

$$
\begin{gathered}
\frac{\partial Q}{\partial V} \approx-\tilde{\tilde{B}}=\left[\begin{array}{ccc}
B_{m+1, m+1} & \ldots & B_{m+1, n} \\
\vdots & \vdots & \vdots \\
B_{n, m+1} & \ldots & B_{n n}
\end{array}\right] \\
M(x)=\left[\begin{array}{cc}
-\tilde{B} & 0 \\
0 & -\tilde{B}
\end{array}\right]
\end{gathered}
$$

## DC Power Flow Analysis

Assumption: small deviation flat voltage profile, $V_{i} \approx 1$ and $\theta_{i} \approx 0$

$$
\frac{\partial P}{\partial \theta} \approx-\tilde{B}
$$

The ultimate steady state: $P=P_{0}+\partial P, \theta=\theta_{0}+\partial \theta$.
In the flat voltage profile, $P_{0}=0, \theta_{0}=0$

$$
P \approx-\tilde{B} \theta
$$

## Matpower

- http://www.pserc.cornell.edu/matpower/
- runpf: run power flow analysis
- runopf: solves an optimal power flow
- makeYbus: Builds the bus admittance matrix and branch admittance matrices.


## PowerWorld



IEEE 14-Bus System


## PowerWorld, cont'd



## ECE ILLINOIS

## Thanks

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